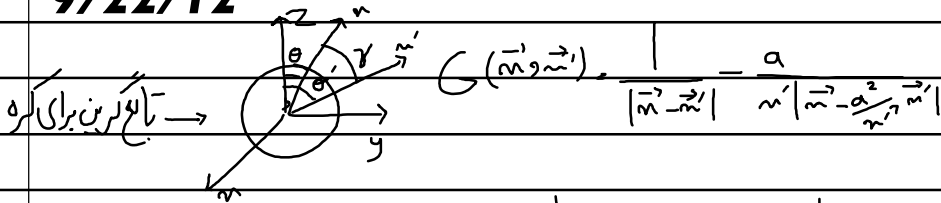
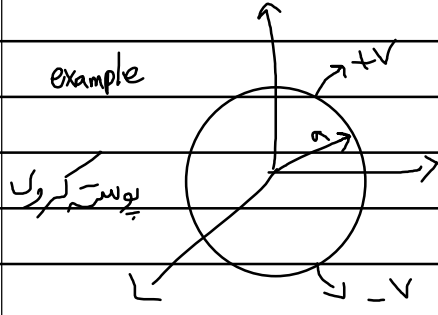


9/22/12



$$G(\vec{m}, \vec{m}') = \frac{1}{\sqrt{m^2 + m'^2 - 2mm' \cos \gamma}} = \frac{1}{\sqrt{m^2 + m'^2 - 2mm' \frac{m^2 + m'^2 - a^2}{m^2 m'^2}}}$$

$$\cos \gamma = \cos \theta \cos \theta' + \sin \theta \sin \theta' \cos(\phi - \phi')$$



example $m < a \Rightarrow \Phi(m) = ?$

$$\Phi(\vec{r}) = \frac{1}{4\pi} \oint_S \Phi(\vec{r}') \frac{\partial}{\partial n'} G(\vec{r}, \vec{r}') da'$$

$$= \frac{1}{4\pi} \int_0^{2\pi} \int_0^{\pi} \Phi(\vec{r}') \frac{\partial}{\partial n'} (|\vec{r} - \vec{r}'|) a^2 \sin \theta' d\theta' d\phi'$$

$$\rightarrow \frac{m^2 - a^2}{a(m^2 + a^2 - 2am \cos \gamma)^{3/2}}$$

$$\Phi(\vec{r}) = \begin{cases} +v & 0 < \theta < \pi/2 \\ -v & \pi/2 < \theta < \pi \end{cases}$$

$$\Rightarrow \Phi(\vec{r}) = \frac{1}{4\pi} \left[\int_0^{2\pi} \int_0^{\pi/2} v \frac{a^2 \sin \theta' d\theta' d\phi'}{a(m^2 + a^2 - 2am \cos \gamma)^{3/2}} + \int_0^{2\pi} \int_{\pi/2}^{\pi} -v \frac{a^2 \sin \theta' d\theta' d\phi'}{a(m^2 + a^2 - 2am \cos \gamma)^{3/2}} \right]$$

$$\Rightarrow \Phi(\vec{r}) = \frac{-a(m^2 - a^2)}{4\pi} \left[\int_0^{2\pi} \int_0^{\pi/2} \frac{v \sin \theta' d\theta' d\phi'}{(m^2 + a^2 - 2am \cos \gamma)^{3/2}} \right]$$

$$- \int_0^{2\pi} \int_{\pi/2}^{\pi} \frac{v \sin \theta' d\theta' d\phi'}{(m^2 + a^2 - 2am \cos \gamma)^{3/2}}$$

$$\Phi(\vec{r}) = \frac{-av(z^2 - a^2)}{2} \left[\int_0^{\pi/2} \frac{\sin \theta'}{(z^2 + a^2 - 2az \cos \theta')^{3/2}} - \int_{\pi/2}^{\pi} \frac{\sin \theta'}{(z^2 + a^2 - 2az \cos \theta')^{3/2}} \right]$$

$$\Rightarrow \Phi(\vec{r}) = \frac{a \cdot V(z^2 - a^2)}{2} \left(\frac{-1}{a^2} \right) \left[\frac{1}{\sqrt{z^2 + a^2}} - \frac{1}{a - z} - \frac{1}{a + z} + \frac{1}{\sqrt{z^2 + a^2}} \right]$$

$$\Rightarrow \Phi(\vec{r}) = \frac{V}{2} \left(a - \frac{a^2 - z^2}{\sqrt{z^2 + a^2}} \right) \quad z < a$$

برای $z > a$ $\rightarrow \Phi(\vec{r}) = \frac{\partial G(\vec{r}, \vec{r}')}{\partial \vec{r}'}$

$$\Rightarrow \Phi(\vec{r}) = \frac{z^2 - a^2}{4\pi a} \left[\int_0^{2\pi} \int_{\frac{\pi}{2}}^{\frac{3\pi}{2}} \frac{V \sin \theta d\theta d\phi a^2}{(z^2 + a^2 - 2az \cos \theta)^{3/2}} + \int_0^{2\pi} \int_{\frac{\pi}{2}}^{\pi} \frac{-V \sin \theta d\theta d\phi a^2}{(z^2 + a^2 - 2az \cos \theta)^{3/2}} \right]$$

$\frac{\partial G(\vec{r}, \vec{r}')}{\partial \vec{r}'} = -\frac{(r^2 - a^2)}{a(r^2 + a^2 - 2ar \cos \theta)^{3/2}}$

$$\Rightarrow \Phi(\vec{r}) = \frac{aV(z^2 - a^2)}{2} \left(\frac{-1}{a^2} \right) \left(\frac{1}{\sqrt{z^2 + a^2}} - \frac{1}{z - a} - \frac{1}{z + a} + \frac{1}{\sqrt{z^2 + a^2}} \right)$$

$$\Rightarrow \Phi(\vec{r}) = V \left(1 - \frac{z^2 - a^2}{z(\sqrt{z^2 + a^2})} \right)$$

حاصل‌تایگرین در دو بُعد:

$$\nabla^2 \Phi(\vec{r}) = -\rho(\vec{r}) / \epsilon_0$$

$$\nabla^2 G(\vec{r}, \vec{r}') = -2\pi \delta(\vec{r} - \vec{r}')$$

انتقال به مختصات قطبی $\vec{r}' = (r', \phi')$

$$\nabla^2 G(\vec{r}) = -2\pi \delta(\vec{r}) = -2\pi \delta(r) \delta(\phi) \Rightarrow \nabla^2 G(r) = -2\pi \delta(r) \frac{1}{|J|} \Rightarrow \nabla^2 G(r) = -\frac{2\pi}{2\pi r} \delta(r) \Rightarrow \nabla^2 G(r) = -\frac{1}{r} \delta(r)$$

$|J| = \int_0^{2\pi} |J| d\phi = \int_0^{2\pi} R d\phi = 2\pi R$

$$\nabla^2 G(r) = -\frac{1}{r} \delta(r) \Rightarrow \frac{1}{r} \frac{d}{dr} \left(r \frac{dG(r)}{dr} \right) = -\frac{1}{r} \delta(r)$$

$r \neq 0 \Rightarrow \frac{d}{dr} \left(r \frac{dG(r)}{dr} \right) = 0 \Rightarrow r \frac{dG(r)}{dr} = C_1 \Rightarrow \frac{dG(r)}{dr} = \frac{C_1}{r} \Rightarrow G(r) = C_1 \ln r + C_2$

$$\nabla^2 G(r) = \frac{1}{r} \delta(r) \Rightarrow \int_V \nabla^2 G(r) d^3\vec{r} = \int_V \frac{1}{r} \delta(r) d^3\vec{r}$$

$$\Rightarrow \int_V \vec{\nabla} \cdot \vec{\nabla} G(r) d^3\vec{r} = - \int_V \frac{1}{r} \delta(r) d^3\vec{r} \Rightarrow \oint_S \vec{\nabla} G(r) \cdot \hat{n} da = - \int_V \frac{1}{r} \delta(r) d^3\vec{r} \Rightarrow$$

$$\oint_S \frac{C_1}{r} \hat{r} \cdot \vec{r} d\phi dz \hat{a}_z = - \int_V \frac{1}{r} \delta(r) r dr d\phi dz$$

$$\Rightarrow C_1 \int_0^{2\pi} d\phi \int_0^h dz = -2\pi h \Rightarrow C_1 2\pi h = -2\pi h \Rightarrow C_1 = -1$$

$$G(r) = -\ln r + C_2$$

$$G(r)|_{r=R} = 0 \Rightarrow -\ln R + C_2 = 0 \Rightarrow C_2 = \ln R$$

$$\Rightarrow G(r) = -\ln r + \ln R$$

$$\nabla^2 G(\vec{r}) = -2\pi \delta(\vec{r})$$

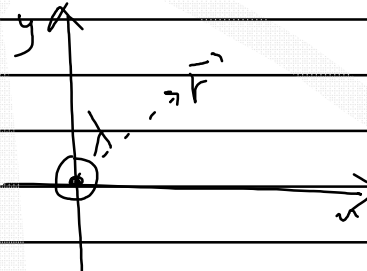
$$\nabla^2 \Phi(\vec{r}) = -\rho(\vec{r})/\epsilon_0$$

$$\vec{r}' = 0 \Rightarrow \nabla^2 G(\vec{r}) = -2\pi \delta(\vec{r}) \Rightarrow G(\vec{r}) = -\ln |\vec{r}| + \ln R$$

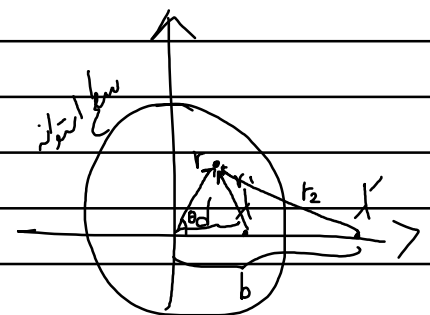
$$\vec{r}' \neq 0 \Rightarrow G(\vec{r}, \vec{r}') = -\ln |\vec{r} - \vec{r}'|$$

تأخیر گرین برای دو بعد
بدون ربع متری

● محاسبه تأخیر گرین برای یک دایره در صفحه xy



example



$$\epsilon_0 \cdot E \cdot 2\pi r l = \lambda l$$

$$\Rightarrow E = \frac{\lambda}{2\pi \epsilon_0 r} \Rightarrow \vec{E} = \frac{\lambda}{2\pi \epsilon_0 r} \hat{a}_r$$

$$\Phi(\vec{r}) = \int_{R_0}^r \vec{E} \cdot d\vec{l} = \int_{R_0}^r \frac{\lambda}{2\pi \epsilon_0 r} \hat{a}_r \cdot dr \hat{a}_r$$

$$\Rightarrow \Phi(\vec{r}) = \frac{\lambda}{2\pi \epsilon_0} \ln \frac{R_0}{r} = -\frac{\lambda}{2\pi \epsilon_0} \ln \frac{r}{R_0} \xrightarrow{\lambda \rightarrow 2\pi \epsilon_0} G(\vec{r}, \vec{r}') = -\ln \frac{r}{R_0}$$

$$\vec{E}_1 = \frac{\lambda}{2\pi \epsilon_0 R} \hat{a}_R \Rightarrow \Phi_1 = -\int_{R_0}^{R_1} \vec{E}_1 \cdot d\vec{l} = -\int_{R_0}^{R_1} \frac{\lambda}{2\pi \epsilon_0 R} \hat{a}_R \cdot dR \hat{a}_R = -\frac{\lambda}{2\pi \epsilon_0} \ln \frac{R_1}{R_0}$$

$$\vec{E}_2 = \frac{\lambda'}{2\pi \epsilon_0 R'} \hat{a}_{R'} \Rightarrow \Phi_2 = -\int_{R'_0}^{R'_2} \vec{E}_2 \cdot d\vec{l} = -\int_{R'_0}^{R'_2} \frac{\lambda'}{2\pi \epsilon_0 R'} \hat{a}_{R'} \cdot dR' \hat{a}_{R'} = -\frac{\lambda'}{2\pi \epsilon_0} \ln \frac{R'_2}{R'_0}$$

$$\Rightarrow \Phi = \Phi_1 + \Phi_2 = -\frac{\lambda}{2\pi \epsilon_0} \ln \frac{r_1}{R_0} - \frac{\lambda'}{2\pi \epsilon_0} \ln \frac{r_2}{R'_0}$$

$$\Phi = -\frac{\lambda}{2\pi \epsilon_0} \ln \sqrt{r^2 + d^2 - 2rd \cos \theta} - \frac{\lambda'}{2\pi \epsilon_0} \ln \sqrt{r'^2 + b^2 - 2rb \cos \theta} + \frac{\lambda}{2\pi \epsilon_0} \ln R_0 + \frac{\lambda'}{2\pi \epsilon_0} \ln R'_0$$

احمال برابر
در نقطه
مابین

$$\Phi(\vec{r}) \Big|_{|\vec{r}|=a} = 0 \Rightarrow -\frac{\lambda}{2\pi \epsilon_0} \ln \sqrt{a^2 + d^2 - 2ad \cos \theta} - \frac{\lambda'}{2\pi \epsilon_0} \ln \sqrt{a^2 + b^2 - 2ab \cos \theta} + \frac{\lambda}{2\pi \epsilon_0} \ln R_0 + \frac{\lambda'}{2\pi \epsilon_0} \ln R'_0 = 0$$

$$\Rightarrow -\frac{\lambda}{2\pi \epsilon_0} \ln \sqrt{a^2 + d^2 - 2ad \cos \theta} - \frac{\lambda'}{2\pi \epsilon_0} \ln \frac{a}{d} \sqrt{d^2 + \frac{b^2 d^2}{a^2} - 2 \frac{bd^2}{a} \cos \theta} + \frac{\lambda}{2\pi \epsilon_0} \ln R_0 + \frac{\lambda'}{2\pi \epsilon_0} \ln R'_0 = 0 \Rightarrow$$

$$a^2 = \frac{b^2 d^2}{a^2} \Rightarrow b^2 = \frac{a^4}{d^2} \Rightarrow b = \frac{a^2}{d}$$

$$\Rightarrow -\frac{\lambda}{2\pi\epsilon_0} \ln \sqrt{a^2 + d^2 - 2ad \cos \theta} - \frac{\lambda'}{2\pi\epsilon_0} \ln \frac{a}{d} - \frac{\lambda'}{2\pi\epsilon} \ln \sqrt{a^2 + d^2 - 2ad \cos \theta} + \frac{\lambda}{2\pi\epsilon_0} \ln R_0 + \frac{\lambda'}{2\pi\epsilon_0} \ln R'_0 = 0$$

$$\downarrow$$

$$-\frac{1}{2\pi\epsilon_0} \ln \sqrt{a^2 + d^2 - 2ad \cos \theta} (\lambda + \lambda') = 0 \quad \left(\begin{array}{l} \lambda + \lambda' = 0 \\ \lambda' = -\lambda \end{array} \right) !$$

$$\frac{\lambda}{2\pi\epsilon_0} \ln \frac{a}{d} + \frac{\lambda}{2\pi\epsilon} \ln R_0 - \frac{\lambda}{2\pi\epsilon} \ln R'_0 = 0$$

$$\ln \left(\frac{a}{d} \cdot R_0 \cdot \frac{1}{R'_0} \right) = 0 \Rightarrow \ln a R_0 = \ln d R'_0 \Rightarrow \frac{a R_0}{d R'_0} = 1 \Rightarrow R'_0 = \frac{a R_0}{d}$$

$$\Phi = -\frac{\lambda}{2\pi\epsilon} \ln \sqrt{r^2 + d^2 - 2rd \cos \theta} - \frac{\lambda'}{2\pi\epsilon} \ln \sqrt{r^2 + \frac{a^4}{d^2} - 2r \frac{a^2}{d} \cos \theta} + \frac{\lambda}{2\pi\epsilon} \ln R_0 + \frac{\lambda'}{2\pi\epsilon_0} \ln R'_0$$

$$\Phi(\vec{r}) = -\frac{\lambda}{2\pi\epsilon_0} \ln \sqrt{r^2 + d^2 - 2rd \cos \theta} + \frac{\lambda}{2\pi\epsilon_0} \ln \frac{d}{a} \Rightarrow G(\vec{r}, \vec{r}') = \Phi(\vec{r}) \Big|_{\lambda \rightarrow 2\pi\epsilon_0}$$

$$\Rightarrow \Phi(\vec{r}) = \frac{\lambda}{2\pi\epsilon_0} \ln \frac{\sqrt{r^2 + \frac{a^4}{d^2} - 2r \frac{a^2}{d} \cos \theta}}{\sqrt{r^2 + d^2 - 2rd \cos \theta}} + \frac{\lambda}{2\pi\epsilon_0} \ln \frac{d}{a} \Rightarrow G(\vec{r}, \vec{r}') = \Phi(\vec{r}) \Big|_{\lambda \rightarrow 2\pi\epsilon_0} =$$

$$\ln \left(\frac{d \sqrt{r^2 + \frac{a^4}{d^2} - 2r \frac{a^2}{d} \cos \theta}}{a \sqrt{r^2 + d^2 - 2rd \cos \theta}} \right)$$

$$G(\vec{r}, \vec{r}') = \ln \left(\frac{d \sqrt{r^2 + \frac{a^4}{d^2} - 2r \frac{a^2}{d} \cos \theta}}{a \sqrt{r^2 + d^2 - 2rd \cos \theta}} \right) \Rightarrow G(\vec{r}, \vec{r}') = \ln \left(\frac{r' \left| \frac{\vec{r}}{r} - \frac{\vec{a}}{a} \right|}{a \left| \frac{\vec{r}}{r} - \frac{\vec{a}}{a} \right|} \right) = \ln \left(\frac{r' \left| \frac{\vec{r}}{r} - \frac{\vec{a}}{a} \right|}{a \left| \frac{\vec{r}}{r} - \frac{\vec{a}}{a} \right|} \right)$$

$$\text{Sog)} \Rightarrow G(\vec{r}, \vec{r}') = -\ln \left| \frac{\vec{r}}{r} - \frac{\vec{a}}{a} \right| + \ln \left| \frac{\vec{r}'}{r'} - \frac{\vec{a}}{a} \right| + C \rightarrow \vec{a} = \frac{a^2}{r^2} \vec{r}$$

$$G(\vec{r}, \vec{r}') = \ln \frac{\left| \frac{\vec{r}}{r} - \frac{\vec{a}}{a} \right|}{\left| \frac{\vec{r}'}{r'} - \frac{\vec{a}}{a} \right|} + C = \ln \frac{\sqrt{\frac{r^2 + \frac{a^4}{r^4} - 2 \frac{a^2}{r^2} \cos(\theta - \theta')}}}{\sqrt{r^2 + r'^2 - 2 r r' \cos(\theta - \theta')}} + C$$

$$G(\vec{r}, \vec{r}') \Big|_{r=a} = 0 \Rightarrow \ln \frac{a}{r'} \sqrt{\frac{a}{a}} + C \Rightarrow C = -\ln \frac{a}{r'}$$

$$G(\vec{r}, \vec{r}') = \ln \left(\frac{r' \left| \frac{\vec{r}}{r} - \frac{\vec{a}}{a} \right|}{a \left| \frac{\vec{r}}{r} - \frac{\vec{a}}{a} \right|} \right)$$

$$y'' - y' - 2y = 2x^2 - 3$$

$$y(-1) = y(0) = 0$$

$$\Rightarrow G(m,s) \begin{cases} C_1 e^x + C_2 e^{-2x} & m < s \\ C_3 e^x + C_4 e^{-2x} & m > s \end{cases}$$

$$G'(m,s) + G(m,s) - 2G(m,s) = \delta(m-s)$$

$$G'_+ + G'_- - 2G = 0 \quad (s \neq x)$$

$$\rightarrow G(-1,s) = 0 \rightarrow C_1 e^{-1} + C_2 e^{-2} = 0$$

$$G(0,s) = 0 \rightarrow C_3 + C_4 = 0$$

$$G(m,s) \Big|_{s^+} = G(m,s) \Big|_{s^-} \rightarrow C_1 e^s + C_2 e^{-2s} = C_3 e^s + C_4 e^{-2s}$$

$$G(m,s) \Big|_{s^+} - G(m,s) \Big|_{s^-} = 1 \rightarrow$$

$$C_3 e^s - 2C_4 e^{-2s} - (C_1 e^s - 2C_2 e^{-2s}) = 1$$

$$y(x) = \int_{-1}^0 G(m,s) f(s) ds + \int_{-1}^x (C_3 e^x + C_4 e^{-2x}) (2s^2 - 3) ds + \int_x^0 (C_1 e^x + C_2 e^{-2x}) (2s^2 - 3) ds$$

Home work

$$\begin{cases} y'' = f(x) \\ y(0) = 1 \\ y(1) = 2 \end{cases}$$

تابع گزین را برست آورید
نسخه $y(x)$ را برست آورید!

$$G'' = \delta(x,s)$$

$$G'' = 0 \quad (m \neq s) \Rightarrow \begin{cases} G = Ax + C & m > s \\ G = Bx + D & m < s \end{cases}$$

$$L[y] = f \quad \int f(s) [G(x,s)] ds$$

$$L[G] = f = y''$$

⚠ تابع گزین برای شرط مرزی ضمنی صدق است فقط [تابع گزین در ابتدا]

$$\Rightarrow \begin{matrix} \text{تعیین در ابتدا} \\ \text{شرط مرزی ضمنی} \end{matrix} \rightarrow y = u + v \quad \begin{cases} u'' + v'' = f(x) \\ u(0) + v(0) = 1 \\ u(1) + v(1) = 2 \end{cases} \rightarrow \begin{cases} u'' = f(x) \\ u(0) = 0 \\ u(1) = 0 \end{cases} \& \begin{cases} v'' = 0 \\ v(0) = 1 \\ v(1) = 2 \end{cases}$$

$$1 \rightarrow G(m, s) = \begin{cases} (s-1)^m & m < s \\ (s)(m-1) & m > s \end{cases}$$

$$2 \rightarrow V = C_1 x + C_2$$

$$C_2 = 1 \rightarrow C_1 = 1$$

$$C_1 + C_2 = 2$$

$$\rightarrow V(m) = m+1$$

$$y(m) = \int_0^m s(m-1) f(s) ds + \int_m^1 (s-1)^m f(s) ds + (m+1)$$

$$\Rightarrow y(m) = (m-1) \int_0^m s f(s) ds + x \int_m^1 (s-1) f(s) ds + (m+1)$$

orthogonal توابع

$U_n(\xi)$ ($n=1, 2, 3, \dots$) orthonormal

در فاصله (a, b) با هم متعامدند

اگر توابع U_n به صورت مجزای در این فاصله
انتقال پذیر باشند. در جاهای دیگر تکرار می‌باشند

$$\int_a^b U_n^*(\xi) U_m(\xi) d\xi = \delta_{mn}$$

Voice ...

if $f(\xi)$ انتقال پذیر
محدود باشد
در این فاصله $\rightarrow f(\xi) \approx \sum_{m=1}^N A_m U_m(\xi) \Rightarrow A = \int_a^b |f(\xi) - \sum_{m=1}^N A_m U_m(\xi)|^2 d\xi$

$$A_{min} \Rightarrow \boxed{\text{مینیمم}}$$

$$A_m = \int_a^b f(\xi) U_m^*(\xi) d\xi$$

$$\Rightarrow f(\xi) = \sum_{m=1}^N A_m U_m(\xi) \quad \boxed{\infty} \text{ voice}$$

اگر $U_n(\xi)$ غیر کرای
کامل باشد $\rightarrow f(\xi) = \sum_{m=1}^{\infty} A_m U_m(\xi)$
- یا اینکه $f(\xi)$ می‌تواند

$$\rightarrow f(\xi) = \sum_{m=1}^{\infty} A_m U_m(\xi) \Rightarrow f(\xi) = \sum_{m=1}^{\infty} \int_a^b f(\xi') U_m^*(\xi') d\xi' U_m(\xi)$$

$$f(\xi) = \int_a^b \sum_{m=1}^{\infty} U_m^*(\xi') U_m(\xi) f(\xi') d\xi' \quad \boxed{\infty} \text{ Voice}$$

$$\delta(\xi - \xi')$$

$$\Rightarrow \sum_{m=1}^{\infty} U_m^*(\xi') U_m(\xi) = \delta(\xi - \xi') \quad \checkmark$$

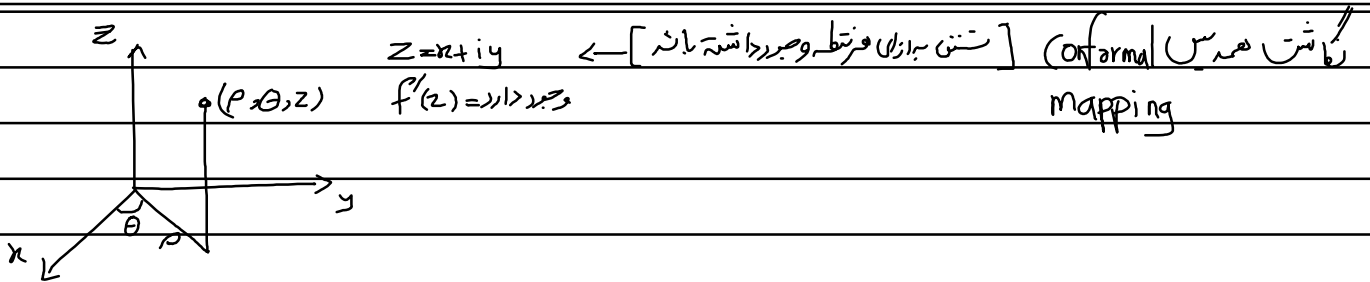
برای این نیز میزوری $\rightarrow \boxed{\infty}$ $(-\frac{a}{2}, \frac{a}{2})$ $U_m = \frac{1}{\sqrt{a}} e^{\frac{i(2\pi m)x}{a}}$; $m = 0, \pm 1, \pm 2$

$$f(x) = \sum_m A_m U_m(x) \Rightarrow f(x) = \sum_m A_m \frac{1}{\sqrt{a}} e^{\frac{i(2\pi m)x}{a}}$$

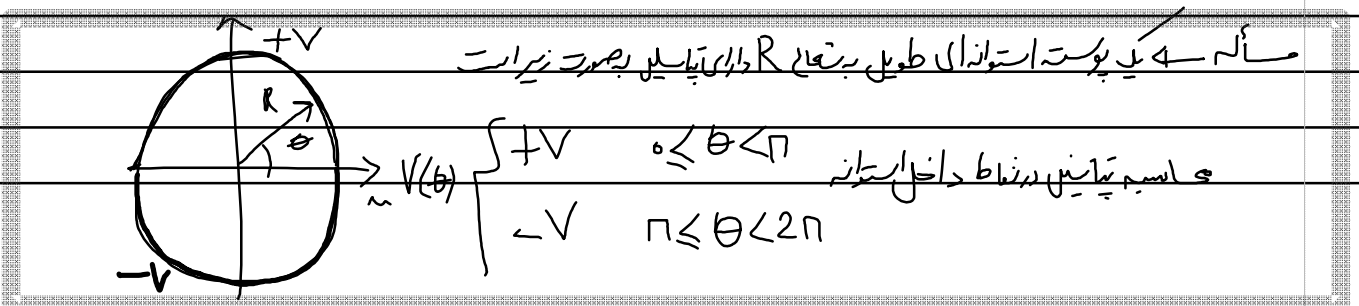
$$A_m = \frac{1}{\sqrt{a}} \int_{-a/2}^{a/2} f(x') e^{-\frac{i(2\pi m)x'}{a}} dx'$$

$$\frac{2\pi m}{a} \equiv k \quad \left| \rightarrow \sum_m \rightarrow \int_{-\infty}^{+\infty} dm \Rightarrow dm = \frac{a}{2\pi} dk$$

$$f(x) = \int_{-\infty}^{+\infty} \frac{a dk}{2\pi} \frac{1}{\sqrt{a}} e^{ikx} \sqrt{\frac{2\pi}{a}} dk \Rightarrow f(x) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{+\infty} e^{ikx} A(k) dk$$



بسیار $\Rightarrow \phi = \phi(\rho, \theta)$
 $\nabla^2 \phi(\rho, \theta) = 0 \Rightarrow \phi(\rho, \theta) = a_0 + b_0 \ln \rho + \sum_{n=1}^{\infty} \rho^n (a_n \sin n\theta + b_n \cos n\theta) + \rho^{-n} (c_n \sin n\theta + d_n \cos n\theta)$



تایم (ازینجا) → حل
در داخل استوانه

$$\Phi(r, \varphi) = a_0 + b_0 \ln r + \sum_{n=1}^{\infty} \left[r^n (a_n \cos n\varphi + b_n \sin n\varphi) + r^{-n} (c_n \cos n\varphi + d_n \sin n\varphi) \right]$$

$$\frac{\Phi}{r=0} \text{ محدود باشد } \Rightarrow b_0 = 0$$

$$c_n = d_n = 0$$

$$\Phi(r, \varphi) = a_0 + \sum_{n=1}^{\infty} r^n (a_n \cos n\varphi + b_n \sin n\varphi)$$

$$\Phi(R, \varphi) = f(\varphi) = a_0 + \sum_{n=1}^{\infty} R^n (a_n \cos n\varphi + b_n \sin n\varphi) \xrightarrow{\int_0^{2\pi}} \int_0^{2\pi} f(\varphi) d\varphi = a_0 2\pi \rightarrow a_0 = \frac{1}{2\pi} \int_0^{2\pi} f(\varphi) d\varphi$$

$$\int_0^{2\pi} f(\varphi) \cos m\varphi d\varphi = a_0 \int_0^{2\pi} \cos m\varphi d\varphi + \sum_{n=1}^{\infty} R^n \left[a_n \int_0^{2\pi} \cos m\varphi \cos n\varphi d\varphi + b_n \int_0^{2\pi} \cos m\varphi \sin n\varphi d\varphi \right] \Rightarrow$$

$$\Rightarrow a_n \int_0^{2\pi} f(\varphi) \cos m\varphi d\varphi = R^n a_n \pi \rightarrow$$

$$a_n = \frac{1}{R^n \pi} \int_0^{2\pi} f(\varphi) \cos n\varphi d\varphi$$

$$b_n = \frac{1}{R^n \pi} \int_0^{2\pi} f(\varphi) \sin n\varphi d\varphi$$

$$a_0 = \frac{1}{2\pi} \left[\int_0^{\pi} V d\varphi + \int_{\pi}^{2\pi} (-V) d\varphi \right] = 0$$

$$a_n = \frac{1}{\pi R^n} \left[\int_0^{\pi} V \cos n\varphi d\varphi + \int_{\pi}^{2\pi} (-V) \cos n\varphi d\varphi \right] = 0$$

$$b_n = \frac{1}{\pi R^n} \left[\int_0^{\pi} V \sin n\varphi d\varphi + \int_{\pi}^{2\pi} (-V) \sin n\varphi d\varphi \right] \Rightarrow b_n = \begin{cases} 0 & \text{زوج} \\ \frac{4V}{\pi R^n} & \text{فرد} \end{cases}$$

$$\Phi(r, \varphi) = \frac{4V}{\pi} \sum_{n=1,3,5,\dots}^{\infty} r^n \sin n\varphi \frac{1}{R^n}$$

$$\Phi_1 = \frac{4V}{\pi} \sum_{n=1,3,5,\dots}^{\infty} \frac{r^n \sin n\varphi}{R^n} \frac{1}{n \cdot R^n}$$

$(re^{i\varphi})^n = z^n$

$$\Phi = \int_m(\Phi_1) \quad ; \quad \Phi_1 = \frac{4V}{\pi} \sum_{n=1,3,5,\dots}^{\infty} \frac{1}{n} \left(\frac{z}{R}\right)^n \rightarrow \frac{d\Phi_1}{dz} = \frac{4V}{\pi} \sum_{n=1,3,5,\dots}^{\infty} \frac{1}{n} \cdot n \cdot \frac{1}{R} \left(\frac{z}{R}\right)^{n-1}$$

$$\Rightarrow \frac{d\Phi_1}{dz} = \frac{4V}{\pi R} \sum_{n=1,3,5,\dots}^{\infty} \left(\frac{z}{R}\right)^{n-1} = \frac{4V}{\pi R} \left[1 + \frac{z^2}{R^2} + \frac{z^4}{R^4} + \dots \right] = \frac{4V}{\pi R} \frac{1}{1 - \frac{z^2}{R^2}} = \frac{4VR}{\pi} \frac{1}{R^2 - z^2}$$

$$\left| \frac{z^2}{R^2} \right| = \frac{\rho^2}{R^2} < 1$$

$$\frac{d\Phi_1}{dz} = \frac{4VR}{\pi} \left(\frac{1}{2R} \right) \left(\frac{1}{R-z} + \frac{1}{R+z} \right) = \frac{2V}{\pi} \left(\frac{1}{z+R} + \frac{1}{z-R} \right)$$

$$\Rightarrow \Phi_1 = \frac{2V}{\pi} \ln \frac{z+R}{z-R} \rightarrow \Phi_1 = \frac{2V}{\pi} \ln \frac{x+iy+R}{x+iy-R}$$

$$\Phi_1 = \frac{2V}{\pi} \ln \left(\frac{x+iy+R}{x+iy-R} \cdot \frac{x-R-iy}{x-R-iy} \right) = \frac{2V}{\pi} \ln \left[\frac{x^2+y^2-R^2-i2Ry}{(x-R)^2+y^2} \right] = \frac{2V}{\pi} \ln \left[\frac{\sqrt{(x^2+y^2-R^2)^2+4R^2y^2}}{(x-R)^2+y^2} \right]$$

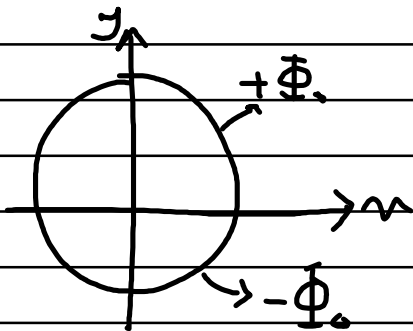
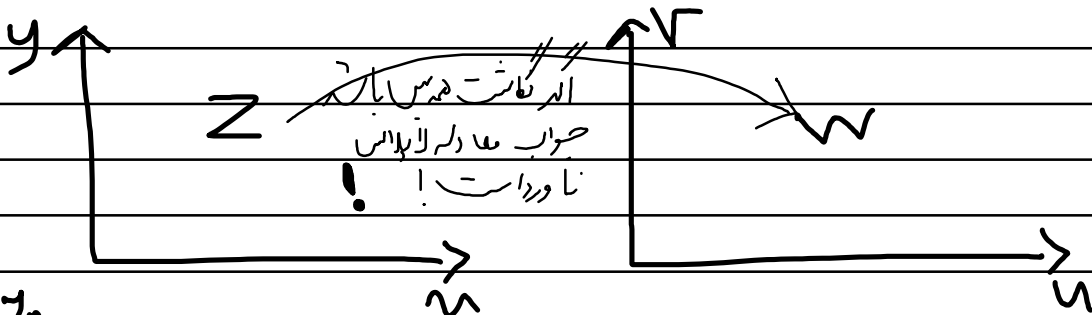
$\times e^{i \tan^{-1} \frac{2Ry}{x^2+y^2-R^2}}$

$$\Rightarrow \Phi_1 = \frac{2V}{\pi} \left[\ln \frac{\sqrt{(x^2+y^2-R^2)^2+4R^2y^2}}{(x-R)^2+y^2} + i \tan^{-1} \frac{-2Ry}{x^2+y^2-R^2} \right]$$

$$\Rightarrow \Phi = \text{Im}(\Phi_1) = \frac{2V}{\pi} \tan^{-1} \frac{2Ry}{x^2+y^2-R^2} \quad R=1 \rightarrow \Phi(x,y) = \frac{2V}{\pi} \tan^{-1} \frac{2y}{1-x^2-y^2} \rightarrow$$

$$\Phi(\rho, \varphi) = \frac{2V}{\pi} \tan^{-1} \frac{2\rho \sin \varphi}{1-\rho^2}$$

Conformal mapping \longrightarrow



$$z = e^{i\theta} \text{ OR } |z|=1$$

$$W(z) = \ln \frac{1+z}{1-z} = \ln(1+z) - \ln(1-z)$$

$$\frac{dW}{dz} = \frac{1}{1+z} - \frac{1}{1-z} = \frac{1-2+1+z}{1-z^2} = \frac{2}{1-z^2}$$

برای متناهی ۱-۱

نگاشت؟ یک نگاشت همسایه است \hookrightarrow

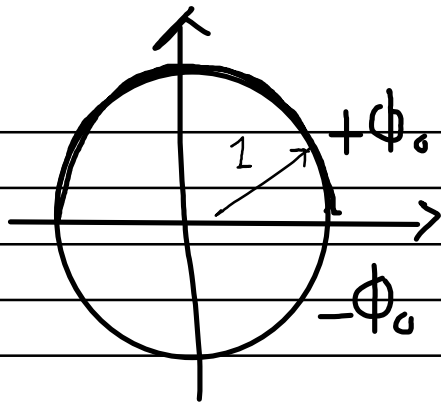
$$W(z) = u + iv = \ln \frac{1+z}{1-z} = \frac{1+x+iy}{1-x-iy} = \ln \left[\frac{1+x+iy}{1-x-iy} \cdot \frac{1-x+iy}{1-x+iy} \right] = \ln \left[\frac{1-x^2-y^2+2iy}{1-2x+x^2+y^2} \right]$$

$$W(z) = \ln \left[\frac{\sqrt{(1-x^2-y^2)^2+4y^2}}{1-2x+x^2+y^2} \right] e^{i \tan^{-1} \frac{2y}{1-x^2-y^2}} \rightarrow W(z) = u(x,y) + iv(x,y) = \ln \frac{\sqrt{(1-x^2-y^2)^2+4y^2}}{1-2x+x^2+y^2} + i \tan^{-1} \frac{2y}{1-x^2-y^2}$$

$$u(x,y)$$

$$v(x,y)$$

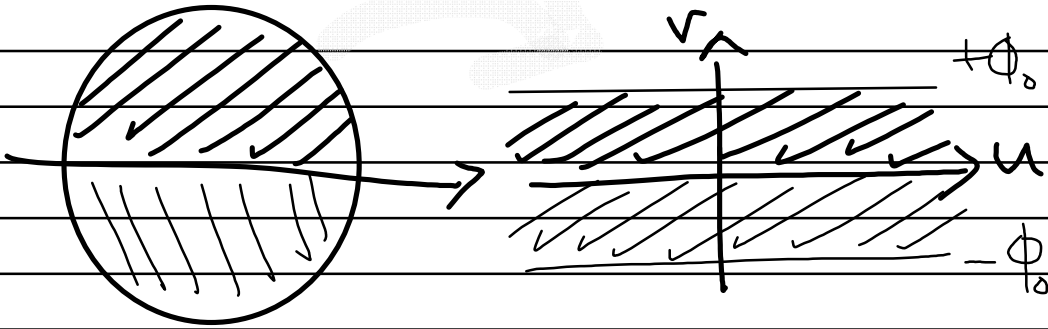
$$\begin{cases} u(x,y) = \ln \frac{\sqrt{(1-x^2-y^2)^2 + 4y^2}}{|1-2x+x^2+y^2|} \\ v(x,y) = \tan^{-1} \frac{2y}{1-x^2-y^2} \end{cases}$$



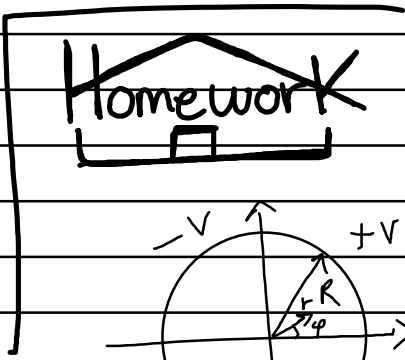
نقطه مثبت $\rho = \sqrt{x^2+y^2} < 1$

نیمه بالایی دایره $\begin{cases} x^2+y^2=1 \\ y>0 \end{cases} \Rightarrow u(x,y) = \ln \frac{2y}{2|1-x|} = \ln \frac{y}{|1-x|}$
 $v(x,y) = \tan^{-1} \frac{2y}{1-x^2-y^2} = \tan^{-1} \infty = \frac{\pi}{2}$

نیمه پایینی $\begin{cases} x^2+y^2=1 \\ y<0 \end{cases} \rightarrow u(x,y) = \ln \left| \frac{y}{1-x} \right|$
 $v(x,y) = \tan^{-1}(-\infty) = -\frac{\pi}{2}$



$$\begin{aligned} \nabla^2 \Phi = 0 &\rightarrow \frac{d^2 \Phi}{dx^2} = 0 \rightarrow \Phi = c_1 x + c_2 \\ \begin{cases} \Phi_0 = c_1 \frac{\pi}{2} + c_2 \\ -\Phi_0 = c_1 (-\frac{\pi}{2}) + c_2 \end{cases} &\rightarrow \begin{cases} c_1 = \frac{2\Phi_0}{\pi} \\ c_2 = 0 \end{cases} \end{aligned} \quad \left. \begin{aligned} \Phi &= \frac{2\Phi_0}{\pi} \tan^{-1} \frac{2y}{1-x^2-y^2} \\ \Phi &= \frac{2\Phi_0}{\pi} \tan^{-1} \frac{2\rho \sin \varphi}{1-\rho^2} \end{aligned} \right\}$$



استازان عزیزم
 طریقی بیرون از R مطابق
 شکل زیر است.
 بیایم در دستاط داخل

جواب $\rightarrow \Phi(r, \varphi) = \frac{2v}{\pi} \tan^{-1} \frac{2R^2 r^2 \sin 2\varphi}{R^4 - r^4} \quad r < R$

با استفاده از همان شکل استازای
 = = روش گشت همس